

Fundamentals of Time Series

Victor A. Bernal Arzola

Based on:

Prof. Zivot open ClassNotes

September, 2015

Erasmus Mundus MSc. Mathematical Modeling

Outline

- 1 Stochastic Processes
- 2 Non- Stationary Process
- 3 Moving Average Processes
- 4 AutoRegressive Processes
- 5 ARMA(1,1) Processes
- 6 Conclusions

Introduction

Time series are sequences of data points, typically consisting of successive measurements made over a time interval.

Time series are used in

- statistics, econometrics, weather forecasting
- mathematical finance and in any domain of applied science involving temporal measurements.

In this lecture we will discuss the Basics of Time Series for AR(1), MA(1), ARMA (1,1)

Stochastic Process

A stochastic process

$$\{Y_1, Y_2, \dots, Y_t, \dots\} = \{Y_t\}_{t=1}^{\infty}$$

is a sequence of random variables indexed by time.

Stochastic Process (II)

A Realization of a stochastic process up to time T

$$\{Y_1 = y_1, Y_2 = y_2, \dots, Y_T = y_T\} = \{y_t\}_{t=1}^T$$

is a sequence of data points y_i indexed by time.

Stochastic Process

There are two important forms of stationarity:

- strictly (or strong) stationarity
- covariance (or weak) stationarity

Strictly Stationary Process

A stochastic process is strictly stationary if for any set $t_1, t_2, t_3, \dots, t_r$ the joint probability distribution of $\{Y_{t_1}, Y_{t_2}, \dots, Y_{t_r}\}$ does not change when shifted in time.

Strictly stationary example

$$\{Y_1, Y_3, Y_{10}\} \sim \{Y_5, Y_7, Y_{14}\}$$

The Joint Distribution is Time shift Invariant!

Covariance Stationary Process

A stochastic process is **Covariance Stationary** if

$$E[Y_t] = \mu \text{ ind } t$$

$$\text{var}(Y_t) = \sigma^2 \text{ ind } t$$

$$\text{cov}(Y_t, Y_{t-j}) = \gamma_j \text{ depends } j$$

the covariance between any two terms of the sequence depends only on the relative positions j of the two terms

Covariance Stationary Process II

The covariance $cov(Y_t, Y_{t-j}) = \gamma_j$ is a measure of the **linear** dependence direction for Y_t, Y_{t-j} . And The Correlation ρ_j defined as

$$\rho_j = \frac{cov(Y_t, Y_{t-j})}{\sqrt{var(Y_t)var(Y_{t-j})}} = \frac{\gamma_j}{\sigma^2}$$

measures its strenght and it satisfies

$$-1 \leq \rho_j \leq 1$$

Gaussian White Noise

A process $\{Y_t\}_{t=1}^{\infty}$ where $Y_t \sim iid N(0, \sigma^2)$ is called Gaussian White Noise *GWN* process and satisfies

$$E[Y_t] = 0 \text{ ind } t$$

$$var(Y_t) = \sigma^2 \text{ ind } t$$

$$cov(Y_t, Y_{t-j}) = 0 \text{ for all } j > 0 \text{ ind } t$$

other types are *Weak-WN* (not ind but just uncorr.) and *Independent-WN* (not gaussian but any distr.)

Gaussian White Noise (II)

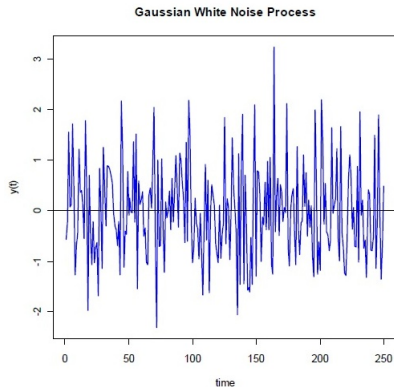


Figure: Gaussian White Noise $GWN(0, 1)$

Non- Stationary Process

In a Non- Stationary Process maybe the mean, the autocovariance or both might depend on t . For Example,

- Trending Process
- Random Walk

The Trending Process

The deterministic trending process is

$$Y_t = \beta_0 + \beta_1 t + \varepsilon_t$$

where

$$\varepsilon_t \sim iid N(0, \sigma_\varepsilon^2)$$

$$E[Y_t] = \beta_0 + \beta_1 t$$
$$var(Y_t) = E[\varepsilon_t]^2 = \sigma_\varepsilon^2$$

the mean is a function of t .

The Trending Process (II)

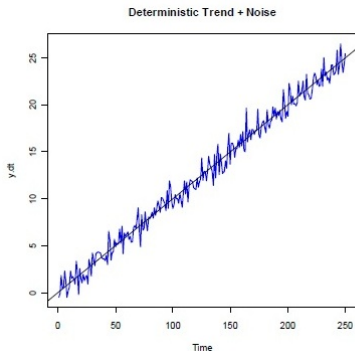


Figure: Deterministic trending $Y_t = 0.1 * t + \epsilon_t$, $\epsilon_t \sim N(0, 1)$

Random Walk

The Random Walk is defined as

$$Y_t = Y_{t-1} + \varepsilon_t$$

where

$$\varepsilon_t \sim iid N(0, \sigma_\varepsilon^2)$$

by recursive substitution

$$Y_t = Y_0 + \sum_{i=1}^t \varepsilon_i$$

Random Walk (II)

Random Walk

$$E[Y_t] = Y_0$$

$$\text{var}(Y_t) = t \cdot \sigma_\varepsilon^2$$

the variance increase linearly as function of t .

Random Walk (III)

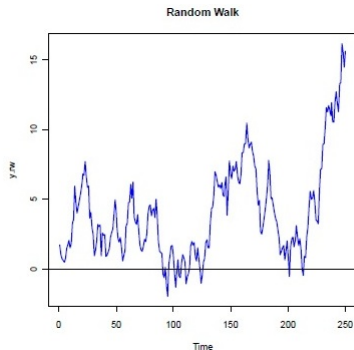


Figure: Random walk $Y_t = Y_{t-1} + \epsilon_t$, $\epsilon_t \sim N(0, 1)$

Example (II)

Let's consider

$$Y_t \sim GWN(0,1) \quad X \sim N(0,1) \quad \text{s.t. } X \perp Y_t$$

then $Z_t = Y_t + X$ implies that

$$\text{var}(Z_t) = 2 \text{ and } \text{cov}(Z_t, Z_{t-j}) = 1$$

$$\Rightarrow \rho_j = \frac{\text{cov}(Y_t, Y_{t-j})}{\sqrt{\text{var}(Y_t)\text{var}(Y_{t-j})}} = \frac{1}{2}$$

for all j . The correlation doesn't vanish with time!

Moving Average Processes

MA(1) is a process in which the correlation last 1 time period

$$Y_t = \mu + \varepsilon_t + \theta\varepsilon_{t-1}$$

$$\varepsilon_t \sim iid N(0, \sigma_\varepsilon^2)$$

Moving Average Processes (II)

MA(1) satisfy

$$E[Y_t] = \mu$$

$$\text{var}(Y_t) = \sigma_\varepsilon^2 (1 + \theta^2)$$

$$\text{cov}(Y_t, Y_{t-1}) = \theta\sigma_\varepsilon^2$$

Moving Average Processes (III)

$$\text{corr}(Y_t, Y_{t-1}) = \frac{\theta}{(1 + \theta^2)}$$

we can observe that

$$\left\{ \begin{array}{ll} \theta = 0 & \rho = 0 \\ \theta > 0 & \rho > 0 \\ \theta < 0 & \rho < 0 \\ |\theta| = 1 & |\rho_{MAX}| = 0.5 \end{array} \right.$$

and that for any j bigger than 1

$$\text{corr}(Y_t, Y_{t-j}) = 0$$

Moving Average Processes (IV)

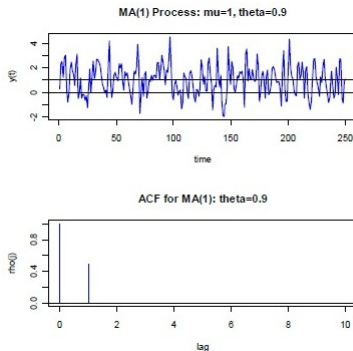


Figure: MA(1) $\mu = 1, \theta = 0.9, \sigma_{\epsilon}^2 = 1$

AutoRegressive Processes

AR(1) Model are

$$Y_t = \mu + \phi (Y_{t-1} - \mu) + \varepsilon_t$$

$$\varepsilon_t \sim iid N(0, \sigma_\varepsilon^2)$$

now the correlation decays to zero progressively if

$$-1 < \phi < 1$$

AutoRegressive Processes (II)

For an AR(1) Model we have

$$E[Y_t] = \mu$$

$$\text{var}(Y_t) = \sigma_\varepsilon^2 / (1 - \phi^2)$$

$$\text{cov}(Y_t, Y_{t-1}) = \frac{\sigma_\varepsilon^2 \phi}{(1 - \phi^2)}$$

$$\text{corr}(Y_t, Y_{t-1}) = \phi$$

AutoRegressive Processes (III)

for any j bigger than 1

$$\text{cov}(Y_t, Y_{t-j}) = \frac{\sigma_\varepsilon^2}{(1 - \phi^2)} \phi^j$$

$$\text{corr}(Y_t, Y_{t-j}) = \phi^j$$

$$\lim_{j \rightarrow \infty} \phi^j = 0$$

the closer is ϕ to unity the stronger the correlation in time

AutoRegressive Processes (IV)

it can be written in the linear regression form (useful for estimation using least squares)

$$Y_t = c + \phi Y_{t-1} + \varepsilon_t$$

where

$$c = \mu(1 - \phi)$$

AutoRegressive Processes (V)

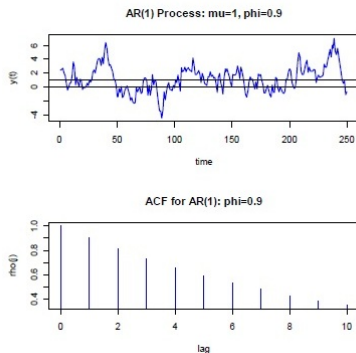


Figure: AR(1) $\mu = 1, \theta = 0.9 \sigma_{\epsilon}^2 = 1$

ARMA(1,1)

An ARMA(1,1) process (sum of MA(1) and AR(1)) is written as

$$Y_t = c + \varepsilon_t + \phi Y_{t-1} + \theta \varepsilon_{t-1}$$

see that if $\phi = 0 \Rightarrow MA(1)$ and if $\theta = 0 \Rightarrow AR(1)$. Then

$$E[Y_t] = c + \phi E[Y_{t-1}]$$

and

$$E[Y_t] = \frac{c}{1 - \phi}$$

ARMA(1,1) II

Now the variance is

$$\text{var}(Y_t) = \frac{(1 + \theta^2 + 2\phi\theta)}{(1 - \phi^2)} \sigma_\epsilon^2$$

and

$$\text{cov}(Y_t, Y_{t-1}) = \phi \text{var}(Y_{t-1}) + \theta \sigma_\epsilon^2 = \frac{(\phi + \theta)(1 + \phi\theta)}{(1 - \phi^2)} \sigma_\epsilon^2$$

Conclusions

We have studied the basic properties of Time Series Processes

- MA(1)
- AR(1)
- ARMA(1,1)

References



E. Zivot. Time Series Concepts. *Manuscript for Introduction to Computational Finance*. 2012